

### Halle 3.0

**W2:** 4th Workshop on mobility solutions – Part 1

**W8:** 4th Workshop on mobility solutions – Part 2

**W15:** Suddenly she knew... **W19:** How can regions get

AAL operational?

**W25:** Your apps and services on the open TAVLA platform

### Halle 2.1

- Registration
- Exhibition
- PosterSession
- Plenary Room & Opening Ceremony

# Halle 9.1.2 / Rosso

**W5**: Is TV really the devil?

**W12:** Hackathons: a good tool or just a trend?

**W16:** Neighbourhoods of the future - Alternative financing

**W23:** Environmental design for houses

**W26:** Merging technical development and an ageing workforce

### Halle 9.0

#### Halle 9.0

- Matchmaking
- Social Dinner

#### Halle 9.0 A

**W1:** AAL living lab within the IBH Network

**W7:** AAL for all: Multi-stakeholder cocreation session

## Halle 9.0

**W13:** Living labs: a new chance for user-oriented and sustainable AAL-innovations?

**W20:** A startup accelerator for the AAL Programme?

**W27:** Public procurement of AAL solutions

- Preliminary lessons learnt from the
STOPandGO project

#### Halle 9.0 B

**W3:** Mobile transformation: Apps and methods from IBM and Apple

**W9:** Supertrends SWOT Matrix

**W14:** Key avenues and challenges for supporting elderly occupation

**W21:** Implementation and upscaling of AAL solutions

**W28:** From recognising motion to emotion awareness - Perspectives for future AAL solutions

#### Halle 9.0 C

**W4:** Building engaging web and mobile solutions – iCareCoops

**W10:** Challenges in matching user needs and ethics issues

**W17:** Creating awareness of AAL technology – Part 2

**W22:** Neighbourhoods of the future - What is possible?

**W29:** Domotics and robotics for Alzheimer's disease

#### Halle 9.0 D

**W6:** Bringing AAL innovation to real life: what investors need

**W11:** Creating awareness of AAL technology – Part 1

**W18:** Back to the future – Visions for age-friendly communities in 2030 and beyond

**W24:** Expectations for AAL and enhanced living environments in 2025/2030

W30: Improving autonomy with robotics